Geometric and probabilistic descriptions of chaotic phase space transport

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MultiSTEPS: MultiScale Transport in Environmental & Physiological Systems, www.multisteps.esm.vt.edu



Motivation: application to real data

- Many systems defined from data or large-scale simulations
 experimental measurements, observations
- e.g., from fluid dynamics, biology, social sciences
- Aperiodic, finite-time, finite resolution
 - in general, no fixed points, periodic orbits, or other invariant sets (or their stable and unstable manifolds) to organize phase space

Motivation: application to real data

- Perhaps can find appropriate analogs to the objects; adapt previous results to ths setting
- Try some numerical explorations; see what merit furthers study

Chaotic phase space transport via lobe dynamics

 \Box As our dynamical system, we consider a discrete map¹ $f: \mathcal{M} \longrightarrow \mathcal{M},$

e.g., $f = \phi_t^{t+T}$, where \mathcal{M} is a differentiable, orientable, two-dimensional manifold e.g., \mathbb{R}^2 , S^2

□ To understand the transport of points under the map *f*, we consider the **invariant manifolds of unstable fixed points**

Let $p_i, i = 1, ..., N_p$, denote a collection of saddle-type hyperbolic fixed points for f.

¹Following Rom-Kedar and Wiggins [1990]

Partition phase space into regions

Natural way to partition phase space

• Pieces of $W^u(p_i)$ and $W^s(p_i)$ partition \mathcal{M} .







Unstable and stable manifolds in **red** and **green**, resp.

Partition phase space into regions

• Intersection of unstable and stable manifolds define boundaries.



Partition phase space into regions

• These boundaries divide the phase space into regions.



Label mobile subregions: 'atoms' of transport

• Can label mobile subregions based on their past and future whereabouts under one iterate of the map, e.g., $(\ldots, R_3, R_3, [R_1], R_1, R_2, \ldots)$



Primary intersection points (pips) and boundaries

 $\Box q$ is a primary intersection point (pip), \overline{q} is not a pip.



Primary intersection points (pips) and boundaries

□ Suppose $W^u(p_i)$ and $W^s(p_j)$ intersect in the pip q. Define $B \equiv U[p_i, q] \bigcup S[p_j, q]$ as a **boundary** between "two sides," R_1 and R_2 .



Lobes: the mobile subregions

Let $q_0, q_1 \in W^u(p_i) \cap W^s(p_j)$ be two adjacent pips, i.e., there are no other pips on $U[q_0, q_1]$ and $S[q_0, q_1]$. The region interior to $U[q_0, q_1] \bigcup S[q_0, q_1]$ is a lobe.



 R_{2}

 $\Box f^{-1}(q)$ is a pip. f is orientation-preserving \Rightarrow there's atleast one pip on $U[f^{-1}(q), q]$ where the $W^u(p_i), W^s(p_j)$ intersection is topologically transverse.

 $f^{-1}(q)$ p_i p_i R_1

 $\Box U[f^{-1}(q), q] \bigcup S[f^{-1}(q), q] \text{ forms boundary of two lobes;}$ one in R_1 , labeled $L_{1,2}(1)$, or equivalently $([R_1], R_2)$, where $f(([R_1], R_2)) = (R_1, [R_2])$, etc. for $L_{2,1}(1)$



- \Box Under one iteration of f, only points in $L_{1,2}(1)$ can move from R_1 into R_2 by crossing B, etc.
- \Box The two lobes $L_{1,2}(1)$ and $L_{2,1}(1)$ are called a **turnstile**.



Essence of lobe dynamics: the dynamics associated with crossing *B* is reduced to the dynamics of the turnstile lobes associated with *B*.



□ In a complicated system, can still identify manifolds ...



Unstable and stable manifolds in red and green, resp.

 \Box ... and lobes



Significant amount of fine, filamentary structure.

- \Box e.g., with three regions $\{R_1, R_2, R_3\}$, label lobe intersections accordingly.
- Denote the intersection $(R_3, [R_2]) \bigcap ([R_2], R_1)$ by $(R_3, [R_2], R_1)$





Longer itineraries...



... correspond to smaller pieces of phase space; horseshoe dynamics, etc

Lobe Dynamics: example

• rest. 3-body problem: chaotic sea contains unstable fixed points.



Compute a boundary



Transport btwn Two Regions

• The evolution of a lobe of species S_1 into R_2

Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Physical Review Letters

Transport btwn Two Regions

Species Distribution: Species S_1 in Region R_2



Lobe dynamics: fluid example

□ Fluid example: time-periodic Stokes flow



streamlines

tracer blob

Lid-driven cavity flow

- Model for microfluidic mixer
- System has parameter τ_f , which we treat as a bifurcation parameter critical point $\tau_f^* = 1$; above and next few slides show $\tau_f > 1$

Computations by Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

Lobe dynamics: fluid example

□ Fluid example: Poincaré map



some invariant manifolds of saddles

Lobe dynamics: fluid example

□ Fluid example: Poincaré map



regions and lobes labeled

Fluid example: Poincaré map



material blob at t = 0

□ Fluid example: Poincaré map



material blob at t = 5

□ Fluid example: Poincaré map



some invariant manifolds of saddles

□ Fluid example: Poincaré map



material blob at t = 10

□ Fluid example: Poincaré map



material blob at t = 15

□ Fluid example: Poincaré map



material blob and manifolds

□ Fluid example: Poincaré map



material blob at t = 20

□ Fluid example: Poincaré map



material blob at t = 25

□ Fluid example: Poincaré map



• Saddle manifolds and lobe dynamics provide template for motion
Stable/unstable manifolds and lobes in fluids

Concentration variance; a measure of homogenization



• Homogenization has two exponential rates: slower one related to lobes

Braiding of stirrers

Large-scale braiding provides the faster scale
— and an alternative point-of-view



 R_N : 2D fluid region with N stirring 'rods'

- stirrers move on periodic orbits
- stirrers = solid objects or fluid particles
- stirrer motions generate diffeomorphism $f: R_N \to R_N$
- stirrer trajectories generate braids in 2+1 dimensional space-time

Thurston-Nielsen classification theorem

- Thurston (1988) Bull. Am. Math. Soc.
- A stirrer motion f is isotopic to a stirrer motion g of one of three types (i) finite order (f.o.): the *n*th iterate of g is the identity (ii) pseudo-Anosov (pA): g has dense orbits, Markov partition with transition matrix A, topological entropy $h_{\mathrm{TN}}(g) = \log(\lambda_{PF}(A))$, where $\lambda_{\mathrm{PF}}(A) > 1 =$ Perron-Frobenius eigenvalue of A (iii) reducible: g contains both f.o. and pA regions
- h_{TN} computed from 'braid word', e.g., $\sigma_{-1}\sigma_{2}$
- $\log(\lambda_{PF}(A))$ provides a **lower bound** on the true topological entropy
- i.e., non-trivial material lines grow like $\ell\sim\ell_0\lambda^n$, where $\lambda\geq\lambda_{\rm TN}$



tracer blob for $\tau_f > 1$

- For $\tau_f > 1$, groups of elliptic and saddle periodic points of period 3 — streamlines around groups resemble fluid mo
 - tion around a solid rod \Rightarrow
- At $\tau_f = 1$, points merge into parabolic points
- Below $\tau_f < 1$, periodic points vanish





Poincaré section for $\tau_f > 1$

• For $\tau_f > 1$, groups of elliptic and saddle periodic points of period 3

— streamlines around groups resemble fluid motion around a solid rod \Rightarrow

- At $\tau_f = 1$, points merge into parabolic points
- Below $\tau_f < 1$, periodic points vanish





Poincaré section for $\tau_f > 1$

- Periodic points of period $3 \Rightarrow act as 'ghost rods'$
- Their braid $\Rightarrow h_{\rm TN} = 0.96242$ from TNCT
- Actual $h_{\mathrm{flow}} \approx 0.964$
- \Rightarrow h_{TN} is an excellent lower bound





- Homogenization has two exponential rates: slower one related to lobes
- Fast rate due to braiding of 'ghost rods'!

Topological entropy continuity across critical point



Identifying 'ghost rods'?



Poincaré section for $\tau_f < 1 \Rightarrow$ no obvious structure!

- Note the absence of any elliptical islands
- No periodic orbits of low period were found
- Is the phase space featureless?

Almost-invariant set (AIS) approach

Take probabilistic point of view (recall, e.g., Oliver Junge's talk)
Partition phase space into loosely coupled regions
AISs ≈ "Leaky" regions with a long residence time²



3-body problem phase space is divided into several invariant and almost-invariant sets.

²Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos

Almost-invariant set (AIS) approach

- Create box partition of phase space $\mathcal{B} = \{B_1, \ldots, B_q\}$, with q large
- Consider a q-by-q transition (Ulam) matrix, P, for our dynamical system, where

$$P_{ij} = \frac{m(B_i \cap f^{-1}(B_j))}{m(B_i)}$$

the transition probability from B_i to B_j using, e.g., $f = \phi_t^{t+T}$



• P approximates our dynamical system via a finite state Markov chain.

Almost-invariant set (AIS) approach

• A set B is called almost invariant over the interval [t, t + T] if

$$\rho(B) = \frac{m(B \cap \phi^{-1}(B))}{m(B)} \approx 1.$$

- Can maximize value of ρ over all possible combinations of sets $B \in \mathcal{B}$.
- In practice, AIS or relatedly, almost-cyclic sets (ACS), identified via eigenvectors (of eigenvalues with $|\lambda| \approx 1$) of P or graph-partitioning
- Appropriate for non-autonomous, aperiodic, finite-time settings



- Return to $\tau_f > 1$ case, where periodic points and manifolds exist
- Agreement between AIS boundaries and manifolds of periodic points
- Known previously³ and applies to more general objects than periodic points, i.e. normally hyperbolic invariant manifolds (NHIMs)

³Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Phys. Rev. Lett.; Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos



Poincaré section for $\tau_f < 1 \Rightarrow$ no obvious structure!

- Return to $\tau_f < 1$ case, where no periodic orbits of low period known • Is the phase space featureless?
- Consider transition matrix $P_t^{t+ au_f}$ induced by Poincaré map $\phi_t^{t+ au_f}$



Top six eigenvalues for $\tau_f = 0.99 < \tau_f^*$



The zero contour (black) is the boundary between the two almost-invariant sets.

- Three-component AIS made of 3 almost-cyclic sets (ACSs) of period 3
- ACS effectively replace compact region bounded by saddle manifolds
- Also a remnant of the global 'stable and unstable manifolds' of the saddle points, even there are no more saddle points

Almost-cyclic sets stirring the surrounding fluid like 'ghost rods' — works even when periodic orbits are absent!

Movie shown is second eigenvector for $P_t^{t+\tau_f}$ for $t \in [0, \tau_f)$



Braid of ACSs gives lower bound of entropy via Thurston-Nielsen

- One only needs approximately cyclic blobs of fluid
- Even though the theorems require exactly periodic points!
- Stremler, Ross, Grover, Kumar [2011] Phys. Rev. Lett.

Topological entropy vs. bifurcation parameter



• h_{TN} shown for ACS braid on 3 strands

Eigenvalues/eigenvectors vs. bifurcation parameter

Movie shows change in eigenvector branch, marked with ' $-\Box$ -' above, as parameter decreases from a to f \Rightarrow

Bifurcation of ACSs

For example, braid on 13 strands for $\tau_f = 0.92$

Movie shown is second eigenvector for $P_t^{t+\tau_f}$ for $t \in [0, \tau_f)$

Thurson-Nielsen for this braid provides lower bound on topological entropy

Bifurcation of ACSs

Bifurcation of ACSs

Sequence of ACS braids bounds entropy

For various braids of ACSs, the calculated entropy is given, bounding from below the true topological entropy over the range where the braid exists

Aperiodic, finite-time setting

- Data-driven, finite-time, aperiodic setting
- How do we get at transport?
- \bullet Recall the flow, $x\mapsto \phi_t^{t+T}(x)$

Identify regions of high sensitivity of initial conditions

• Small initial perturbations $\delta x(t)$ grow like

$$\delta x(t+T) = \phi_t^{t+T}(x+\delta x(t)) - \phi_t^{t+T}(x)$$
$$= \frac{d\phi_t^{t+T}(x)}{dx} \delta x(t) + O(||\delta x(t)||^2)$$

Identify regions of high sensitivity of initial conditions

• Small initial perturbations $\delta x(t)$ grow like

$$\delta x(t+T) = \phi_t^{t+T}(x+\delta x(t)) - \phi_t^{t+T}(x)$$
$$= \frac{d\phi_t^{t+T}(x)}{dx} \delta x(t) + O(||\delta x(t)||^2)$$

• The finite-time Lyapunov exponent (FTLE),

$$\sigma_t^T(x) = \frac{1}{|T|} \log \left\| \frac{d\phi_t^{t+T}(x)}{dx} \right\|$$

measures the maximum stretching rate over the interval T of trajectories starting near the point \boldsymbol{x} at time t

• Ridges of σ_t^T are candidate hyperbolic codim-1 surfaces; finite-time analogs of stable/unstable manifolds; Lagrangian coherent structures⁴

⁴cf. Bowman, 1999; Haller & Yuan, 2000; Haller, 2001; Shadden, Lekien, Marsden, 2005

• We can define the FTLE for Riemannian manifolds 3

$$\sigma_t^T(x) = \frac{1}{|T|} \ln \left\| \mathbf{D}\phi_t^{t+T} \right\| \doteq \frac{1}{|T|} \log \left(\max_{\substack{\mathbf{y}\neq \mathbf{0}}} \frac{\left\| \mathbf{D}\phi_t^{t+T}(\mathbf{y}) \right\|}{\|\mathbf{y}\|} \right)$$

with y a small perturbation in the tangent space at x.

³Lekien & Ross [2010] Chaos

Transport barriers: LCS

• Ridges correspond to dynamical barriers³ or Lagrangian coherent structures (LCS): repelling surfaces for T > 0, attracting for T < 0

cylinder

Moebius strip

Each frame has a different initial time t

³Lekien & Ross [2010] Chaos

Atmospheric flows: Antarctic polar vortex

ozone data

Atmospheric flows: Antarctic polar vortex

ozone data + LCSs (red = repelling, blue = attracting)

Atmospheric flows: Antarctic polar vortex

air masses on either side of a repelling LCS

Atmospheric flows: continental U.S.

LCSs: orange = repelling, blue = attracting


 $\mathsf{orange} = \mathsf{repelling} \ \mathsf{LCSs}, \ \mathsf{blue} = \mathsf{attracting} \ \mathsf{LCSs}$

satellite

Hurricane Andrea, 2007

cf. Sapsis & Haller [2009], Du Toit & Marsden [2010], Lekien & Ross [2010], Tallapragada & Ross [2011]



Hurricane Andrea at one snapshot; LCS shown (orange = repelling, blue = attracting)



orange = repelling (stable manifold), blue = attracting (unstable manifold)



orange = repelling (stable manifold), blue = attracting (unstable manifold)



Portions of lobes colored; magenta = outgoing, green = incoming, purple = stays out



Portions of lobes colored; magenta = outgoing, green = incoming, purple = stays out

Sets behave as lobe dynamics dictates

Coherent sets and set-based definition of FTLE

- Consider, e.g., a flow ϕ_t^{t+T} in $(x_1, x_2) \in \mathbb{R}^2$.
- Treat the evolution of set $B \subset \mathbb{R}^2$ as evolution of two random variables X_1 and X_2 defined by probability density function $f(x_1, x_2)$, initially uniform on B, $f = \frac{1}{\mu(B)} \mathcal{X}_B$, with \mathcal{X}_B the characteristic function of B.
- Under the action of the flow ϕ_t^{t+T} , f is mapped to Pf where P is the associated Perron-Frobenius operator.
- Let I(f) be the covariance of f and I(Pf) the covariance of Pf.



Deformation of a disk under the flow during [t, t+T]

Coherent sets and set-based definition of FTLE

• **Definition.** The **covariance-based FTLE** of *B* is

$$\sigma_{I}(B,t,T) = \frac{1}{|T|} \log \left(\frac{\sqrt{\lambda_{max}(I(Pf))}}{\sqrt{\lambda_{max}(I(f))}} \right)$$

 Reduces to usual definition of FTLE in the limit that the linearization approximation (i.e., line-stretching method) is valid



Deformation of a disk under the flow during [t, t+T]

Coherent sets and set-based definition of FTLE

- The **coherence** of a set B during [t, t + T] is $\sigma_I(B, t, T)$.
- A set B is almost-coherent during [t, t+T] if $\sigma_I(B, t, T) \approx 0$.
- Captures the essential feature of a coherent set: it does not mix or spread significantly in the domain.
- This definition also can identify non-mixing translating sets.
- Values of $\sigma_I(B,t,T)$ determine the family of sets of various degrees of coherence.
- Need to set a heuristic threshold on the value of $\sigma_I(B,t,T)$ to determine coherent sets.
- Notice, coherent sets will be separated by ridges of high FTLE, i.e., LCS



FTLE from line-stretching (conventional) during $[0, \tau_f]$



FTLE from covariance-based approach during $[0, \tau_f]$



Sets of coherences $\sigma_I(0, \tau_f) < 1.6$



Compare with AIS from second eigenvector of P

Coherent sets in the atmosphere



• FTLE from covariance during 24 hours starting 09:00 1 May 2007

Coherent sets in the atmosphere



• Coherent sets during 24 hours starting 09:00 1 May 2007

Final words on chaotic transport

- □ What are robust descriptions of transport which work in data-driven aperiodic, finite-time settings?
 - Possibilities: finite-time lobe dynamics / symbolic dynamics may work
 finite-time analogs of homoclinic and heteroclinic tangles
 - Probabilistic, geometric, and topological methods

 invariant sets, almost-invariant sets, almost-cyclic sets, coherent sets, stable and unstable manifolds, Thurston-Nielsen classification, FTLE, LCS
 - Many links between these notions e.g., LCS locate analogs of stable and unstable manifolds
 - boundaries between coherent sets are naturally LCS
 - periodic points \Rightarrow almost-cyclic sets
 - their 'stable/unstable invariant manifolds' \Rightarrow ???

The End

For papers, movies, etc., visit: www.shaneross.com

Main Papers:

- Stremler, Ross, Grover, Kumar [2011] Topological chaos and periodic braiding of almost-cyclic sets. *Physical Review Letters* 106, 114101.
- Tallapragada & Ross [2011] A geometric and probabilistic description of coherent sets. Preprint.
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- Senatore & Ross [2011] Detection and characterization of transport barriers in complex flows via ridge extraction of the finite time Lyapunov exponent field, International Journal for Numerical Methods in Engineering 86, 1163.
- Grover, Ross, Stremler, Kumar [2011] Topological chaos, braiding and breakup of almost-invariant sets. Preprint.
- Tallapragada & Ross [2008] Particle segregation by Stokes number for small neutrally buoyant spheres in a fluid, *Physical Review E* 78, 036308.