# **Geometry of phase space transport in a variety of mechanical systems**

#### Shane Ross

Engineering Science and Mechanics, Virginia Tech

www.shane ross.com

In collaboration with Piyush Grover, Carmine Senatore, Phanindra Tallapragada, Pankaj Kumar, Mohsen Gheisarieha, David Schmale, Francois Lekien, Mark Stremler

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#### Chaotic phase space transport via lobe dynamics

 $\Box$  As our dynamical system, we consider a discrete map<sup>1</sup>  $f: \mathcal{M} \longrightarrow \mathcal{M},$ 

e.g.,  $f = \phi_t^{t+T}$ , where  $\mathcal{M}$  is a differentiable, orientable, two-dimensional manifold e.g.,  $\mathbb{R}^2$ ,  $S^2$ 

□ To understand the transport of points under the map *f*, we consider the **invariant manifolds of unstable fixed points** 

Let  $p_i, i = 1, ..., N_p$ , denote a collection of saddle-type hyperbolic fixed points for f.

<sup>1</sup>Following Rom-Kedar and Wiggins [1990]

# Partition phase space into regions

Natural way to partition phase space

• Pieces of  $W^u(p_i)$  and  $W^s(p_i)$  partition  $\mathcal{M}$ .







Unstable and stable manifolds in red and green, resp.

# Partition phase space into regions

• Intersection of unstable and stable manifolds define boundaries.



## Partition phase space into regions

• These boundaries divide the phase space into regions.



## Label mobile subregions: 'atoms' of transport

• Can label mobile subregions based on their past and future whereabouts under one iterate of the map, e.g.,  $(\ldots, R_3, R_3, [R_1], R_1, R_2, \ldots)$ 



## Primary intersection points (pips) and boundaries

 $\Box q$  is a primary intersection point (pip),  $\overline{q}$  is not a pip.



## Primary intersection points (pips) and boundaries

□ Suppose  $W^u(p_i)$  and  $W^s(p_j)$  intersect in the pip q. Define  $B \equiv U[p_i, q] \bigcup S[p_j, q]$  as a **boundary** between "two sides,"  $R_1$  and  $R_2$ .



#### Lobes: the mobile subregions

Let  $q_0, q_1 \in W^u(p_i) \cap W^s(p_j)$  be two adjacent pips, i.e., there are no other pips on  $U[q_0, q_1]$  and  $S[q_0, q_1]$ . The region interior to  $U[q_0, q_1] \bigcup S[q_0, q_1]$  is a lobe.



 $R_{2}$ 

 $\Box f^{-1}(q)$  is a pip. f is orientation-preserving  $\Rightarrow$  there's atleast one pip on  $U[f^{-1}(q), q]$  where the  $W^u(p_i), W^s(p_j)$ intersection is topologically transverse.

 $f^{-1}(q)$  $p_i$  $p_i$  $R_1$ 

 $\Box U[f^{-1}(q), q] \bigcup S[f^{-1}(q), q] \text{ forms boundary of two lobes;}$ one in  $R_1$ , labeled  $L_{1,2}(1)$ , or equivalently  $([R_1], R_2)$ , where  $f(([R_1], R_2)) = (R_1, [R_2])$ , etc. for  $L_{2,1}(1)$ 



- $\Box$  Under one iteration of f, only points in  $L_{1,2}(1)$  can move from  $R_1$  into  $R_2$  by crossing B, etc.
- $\Box$  The two lobes  $L_{1,2}(1)$  and  $L_{2,1}(1)$  are called a **turnstile**.



Essence of lobe dynamics: the dynamics associated with crossing *B* is reduced to the dynamics of the turnstile lobes associated with *B*.



□ In a complicated flow, can still identify manifolds ...



Unstable and stable manifolds in red and green, resp.

 $\Box$  ... and lobes



Significant amount of fine, filamentary structure.

- $\Box$  e.g., with three regions  $\{R_1, R_2, R_3\}$ , label lobe intersections accordingly.
- Denote the intersection  $(R_3, [R_2]) \bigcap ([R_2], R_1)$  by  $(R_3, [R_2], R_1)$





Longer itineraries...



... correspond to smaller pieces of phase space; horseshoe dynamics, etc

• Many systems defined from data or large-scale simulations

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  no fixed points or periodic orbits (or their manifolds)

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- Many systems defined from data or large-scale simulations
- e.g., atmospheric winds are a time-chaotic flow field
  no fixed points or periodic orbits (or their manifolds)
- How do we get at transport?
- Recall the flow

$$x \mapsto \phi_{t_0}^{t_0 + T}(x)$$



• Small initial perturbations  $\delta x(t_0)$  grow like

$$\delta x(t_0 + T) = \phi_{t_0}^{t_0 + T}(x + \delta x(t_0)) - \phi_{t_0}^{t_0 + T}(x)$$
$$= \frac{d\phi_{t_0}^{t_0 + T}(x)}{dx} \delta x(t_0) + O(||\delta x(t_0)||^2)$$



## Invariant manifold analogs: FTLE-LCS approach

• The finite-time Lyapunov exponent (FTLE),

$$\sigma_t^T(x) = \frac{1}{|T|} \log \left\| \frac{d\phi_t^{t+T}(x)}{dx} \right\|$$

measures the maximum stretching rate over the interval T of trajectories starting near the point x at time t

• Ridges of  $\sigma_t^T$  are candidate hyperbolic codim-1 surfaces; finite-time analogs of stable/unstable manifolds; Lagrangian coherent structures<sup>2</sup>



<sup>2</sup>cf. Bowman, 1999; Haller & Yuan, 2000; Haller, 2001; Shadden, Lekien, Marsden, 2005

## Invariant manifold analogs: FTLE-LCS approach

• We can define the FTLE for Riemannian manifolds $^3$ 

$$\sigma_t^T(x) = \frac{1}{|T|} \ln \left\| \mathbf{D}\phi_t^{t+T} \right\| \doteq \frac{1}{|T|} \log \left( \max_{\substack{\mathbf{y}\neq 0}} \frac{\left\| \mathbf{D}\phi_t^{t+T}(\mathbf{y}) \right\|}{\|\mathbf{y}\|} \right)$$

with y a small perturbation in the tangent space at x.



<sup>&</sup>lt;sup>3</sup>Lekien & Ross [2010] Chaos

## **Transport barriers: LCS**

• Ridges correspond to dynamical barriers<sup>3</sup> or Lagrangian coherent structures (LCS): repelling surfaces for T > 0, attracting for T < 0

cylinder

Moebius strip

Each frame has a different initial time t

<sup>3</sup>Lekien & Ross [2010] Chaos

## **Atmospheric flows: Antarctic polar vortex**

ozone data

#### Atmospheric flows: Antarctic polar vortex

ozone data + LCSs (red = repelling, blue = attracting)

#### Atmospheric flows: Antarctic polar vortex

air masses on either side of a repelling LCS

#### Atmospheric flows: continental U.S.

LCSs: orange = repelling, blue = attracting

# **Classification of motifs**



- Regions bounded by attracting and repelling curves
- Atmosphere is naturally parsed into discrete 'cells'

# Motion of 'cells'



• Packets have their own dynamics as consequence of repelling and attracting natures of boundaries



 $orange = repelling \ LCSs, \ blue = attracting \ LCSs$ 

satellite

#### Hurricane Andrea, 2007

cf. Sapsis & Haller [2009], Du Toit & Marsden [2010], Lekien & Ross [2010]



Hurricane Andrea at one snapshot; LCS shown (orange = repelling, blue = attracting)



orange = repelling (stable manifold), blue = attracting (unstable manifold)



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#### **Atmospheric flows and lobe dynamics**



Portions of lobes colored; magenta = outgoing, green = incoming, purple = stays out

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Portions of lobes colored; magenta = outgoing, green = incoming, purple = stays out

#### **Atmospheric flows and lobe dynamics**

Sets behave as lobe dynamics dictates

# Invasive species riding the atmosphere

Hurricane Ivan (2004) brought new crop disease (soybean rust) to U.S.



#### From Rio Cauca region of Colombia

#### **Disease extent**

# Invasive species riding the atmosphere

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#### **Disease extent**



Cost of invasive organisms is <u>\$137 billion</u> per year in U.S.

Airborne pathogen 20-300 μm

# Aerial sampling: 40 m – 400 m altitude

Kentland Farm-

©2010 GO

Image © 2010 Commonwealth of Virginia Image © 2010 DigitalGlobe Image USDA Farm Service Agency Image U.S. Geological Survey



#### Pathogen transport: filament bounded by LCS



#### Pathogen transport: filament bounded by LCS



12:00 UTC 1 May 2007

15:00 UTC 1 May 2007

# Lobe dynamics: another fluid example

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



streamlines

tracer blob

Lid-driven cavity flow

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

# Lobe dynamics: another fluid example

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some invariant manifolds of saddles

#### Lid-driven cavity flow

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# Lobe dynamics: another fluid example

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



regions and lobes labeled

<sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 0

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 5

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



some invariant manifolds of saddles

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 10

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 15

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob and manifolds

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 20

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



material blob at t = 25

<sup>&</sup>lt;sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



• Saddle manifolds and lobe dynamics provide template for motion

<sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

 $\Box$  Fluid example: time-periodic Stokes flow<sup>2</sup>



• Homogenization has two exponential rates: slower one related to lobes

<sup>2</sup>Computations of Mohsen Gheisarieha and Mark Stremler (Virginia Tech)

# **Braiding of stirrers**



 $R_N$ : 2D fluid region with N stirring 'rods'

- stirrers move on periodic orbits
- stirrers = solid objects or fluid particles
- stirrer motions generate diffeomorphism  $f: R_N \to R_N$
- stirrer trajectories generate braids in 2+1 dimensional space-time

- Thurston (1988) Bull. Am. Math. Soc.
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  (iii) reducible: g contains both f.o. and pA regions
- $h_{\rm TN}$  computed from 'braid word', e.g.,  $\sigma_{-1}\sigma_{2}$
- $\log(\lambda_{PF}(A))$  provides a **lower bound** on the true topological entropy
- i.e., non-trivial material lines grow like  $\ell\sim\ell_0\lambda^n$  , where  $\lambda\geq\lambda_{\rm TN}$



tracer blob for  $\tau_f > 1$ 

- Bifurcation parameter  $au_f$  to this system
- Critical point  $\tau_f^* = 1$
- For  $\tau_f > 1$ , pairs of elliptic and saddle points
- Below  $\tau_f < 1$ , pairs vanish





Poincaré section for  $\tau_f > 1$ 

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Poincaré section for  $\tau_f > 1$ 

- Periodic points of period  $3 \Rightarrow act as 'ghost rods'$
- Their braid  $\Rightarrow h_{\rm TN} = 0.96242$
- Actual  $h_{\mathrm{flow}} \approx 0.964$
- $h_{\mathrm{TN}}$  is an excellent lower bound





- Homogenization has two exponential rates: slower one related to lobes
- Fast rate due to braiding of ghost rods!

#### **Topological entropy continuity across critical point**



## Identifying 'ghost rods'?



Poincaré section for  $\tau_f < 1 \Rightarrow$  no obvious structure!

- Note the absence of any elliptical islands
- No periodic orbits of low period were found
- Is the phase space featureless?

# Almost-invariant set (AIS) approach

• Partition phase space into loosely coupled regions "Leaky" regions with a long residence time<sup>3</sup>



3-body problem phase space is divided into several invariant and almost-invariant sets.

 $<sup>\</sup>overline{^{3}}$ work of Dellnitz, Junge, Froyland, et al
## Almost-invariant set (AIS) approach

- Create box partition of phase space  $\mathcal{B} = \{B_1, \ldots, B_q\}$ , with q large
- Consider a q-by-q transition (Ulam) matrix, P, for our dynamical system, where

$$P_{ij} = \frac{\mu(B_i \cap f^{-1}(B_j))}{\mu(B_i)},$$

the transition probability from  $B_i$  to  $B_j$  using, e.g.,  $f = \phi_t^{t+T}$ 



• P approximates our dynamical system via a finite state Markov chain.

## Almost-invariant set (AIS) approach

• A set B is called almost invariant over the interval [t, t+T] if

$$\rho_{\mu}(B) = \frac{\mu(B \cap \phi^{-1}(B))}{\mu(B)} \approx 1.$$

Can maximize value of  $\rho_{\mu}$  over all possible combinations of sets  $B \in \mathcal{B}$ .

- In practice, AIS or relatedly, almost-cyclic sets (ACS), identified via **eigenvectors** of P or graph-partitioning
- Appropriate for non-autonomous, aperiodic, finite-time settings



- Return to  $\tau_f > 1$  case, where periodic points and manifolds exist
- Good agreement between AIS boundaries and manifolds of fixed points
- Known previously<sup>4</sup> and applies to more general objects than fixed points, i.e. normally hyperbolic invariant manifolds (NHIMs)

<sup>&</sup>lt;sup>4</sup>Dellnitz, Junge, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Phys. Rev. Lett.; Dellnitz, Junge, Koon, Lekien, Lo, Marsden, Padberg, Preis, Ross, Thiere [2005] Int. J. Bif. Chaos



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Poincaré section for  $\tau_f < 1 \Rightarrow$  no obvious structure!

- Return to  $\tau_f < 1$  case, where no periodic orbits of low period known • Is the phase space featureless?
- Consider transition matrix  $P_t^{t+ au_f}$  induced by Poincaré map  $\phi_t^{t+ au_f}$



Top six eigenvalues for  $\tau_f = 0.99$ 

5



• The disconnected AIS is made of three almost-cyclic sets, with period 3

Almost-cyclic sets stirring the surrounding fluid like 'ghost rods' — works even when periodic orbits are absent!

Movie shown is second eigenvector for  $P_t^{t+\tau_f}$  for  $t \in [0, \tau_f)$ 



Braid of ACSs gives lower bound of entropy via Thurston-Nielsen

- One only needs approximately cyclic blobs of fluid
- Even though the theorems require exactly periodic points!
- Stremler, Ross, Grover, Kumar [2011] Phys. Rev. Lett.

#### **Topological entropy vs. bifurcation parameter**



•  $h_{\mathrm{TN}}$  shown for ACS braid on 3 strands

#### **Eigenvalues/eigenvectors vs. bifurcation parameter**



#### **Bifurcation of ACSs**

For example, braid on 13 strands for  $\tau_f = 0.92$ 

Movie shown is second eigenvector for  $P_t^{t+\tau_f}$  for  $t \in [0, \tau_f)$ 

Thurson-Nielsen for this braid provides lower bound on topological entropy

## **Bifurcation of ACSs**



#### **Bifurcation of ACSs**



## Sequence of ACS braids bounds entropy



For various braids of ACSs, the calculated entropy is given, bounding from below the true topological entropy over the range where the braid exists

- Consider, e.g., a flow  $\phi_t^{t+T}$  in  $(x_1, x_2) \in \mathbb{R}^2$ .
- Treat the evolution of set  $B \subset \mathbb{R}^2$  as evolution of two random variables  $X_1$  and  $X_2$  defined by probability density function  $f(x_1, x_2)$ , initially uniform on B,  $f = \frac{1}{\mu(B)} \mathcal{X}_B$ , with  $\mathcal{X}_B$  the characteristic function of B.
- Under the action of the flow  $\phi_t^{t+T}$ , f is mapped to Pf where P is the associated Perron-Frobenius operator.
- Let I(f) be the covariance of f and I(Pf) the covariance of Pf.



Deformation of a disk under the flow during [t, t+T]

• **Definition.** The **covariance-based FTLE** of *B* is

$$\sigma_{I}(B,t,T) = \frac{1}{|T|} \log \left( \frac{\sqrt{\lambda_{max}(I(Pf))}}{\sqrt{\lambda_{max}(I(f))}} \right)$$

 Reduces to usual definition of FTLE in the limit that the linearization approximation (i.e., line-stretching method) is valid



Deformation of a disk under the flow during [t, t+T]

- The **coherence** of a set B during [t, t + T] is  $\sigma_I(B, t, T)$ .
- A set B is almost-coherent during [t, t+T] if  $\sigma_I(B, t, T) \approx 0$ .

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- Captures the essential feature of a coherent set: it does not mix or spread significantly in the domain.
- This definition also can identify non-mixing translating sets.

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- Need to set a heuristic threshold on the value of  $\sigma_I(B,t,T)$  to determine coherent sets.
- Notice, coherent sets will be separated by ridges of high FTLE, i.e., LCS



FTLE from line-stretching (conventional) during  $[0, \tau_f]$ 



FTLE from covariance-based approach during  $[0, \tau_f]$ 



Sets of coherences  $\sigma_I(0, \tau_f) < 1.6$ 



Compare with AIS from second eigenvector of P

#### Coherent sets in the atmosphere



• FTLE from covariance during 24 hours starting 09:00 1 May 2007

#### **Coherent sets in the atmosphere**



• Coherent sets during 24 hours starting 09:00 1 May 2007

## **Optimal navigation in an aperiodic setting?**

- Selectively 'jumping' between coherent air masses using control
- Moving between mobile subregions of different finite-time itineraries

### Final words on chaotic transport

- □ What are the robust descriptions of transport which work in data-driven aperiodic, finite-time settings?
  - Possibilities: finite-time lobe dynamics, finite-time symbolic dynamics may work
  - For these, use set-oriented approach
  - Many links between invariant manifolds, FTLE, LCS, AIS/coherent sets, and topological methods

— e.g., boundaries between coherent sets are naturally LCS; follows from covariance-based definition of FTLE

— fixed points  $\Rightarrow$  AIS, so stable/unstable invariant manifolds  $\Rightarrow$  ???

# The End

#### For papers, movies, etc., visit: www.shaneross.com

Main Papers:

- Stremler, Ross, Grover, Kumar [2011] Topological chaos and periodic braiding of almost-cyclic sets. *Physical Review Letters* 106, 114101.
- Senatore & Ross [2011] Detection and characterization of transport barriers in complex flows via ridge extraction of the finite time Lyapunov exponent field, International Journal for Numerical Methods in Engineering 86, 1163.
- Lekien & Ross [2010] The computation of finite-time Lyapunov exponents on unstructured meshes and for non-Euclidean manifolds. Chaos 20, 017505.
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